

King Fahd University of Petroleum and Minerals - KFUPM College of Petroleum Engineering and Geosciences - CPG Department of Geosciences



focusing on the energy transition with emphasis on geothermal and reservoir monitoring EOR



Fluid monitoring using joint EM and Seismic methods

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WHY do we present this !!

Carbonate reservoir characterization is challenging because,

- the reservoirs has secondary porosity/fractures
- seismic is challenged by high velocities.
- we want the **fluids** (oil, gas, brine, etc.)

Characterizing fractures needs permeability \rightarrow necessity of <u>directional sensitivity</u>



INTEGRATING surface and borehole geophysical methods. Microseismic with non-seismic (electromagnetic - passive & active) & gravity leads to fracture characterization & fluid flow direction

Seismic delineates **geometric boundaries**, EM gives <mark>fluids</mark> from resistive (hydrocarbons) to water (conductive). Gravity senses density contrasts between fluids, gas & rock matrix.

OBJECTIVES are:

- to understand injected fluid (front) movement/distribution
- to depict flow pattern of fluids
- to define fluid interactions at reservoir level
- to build a reservoir static/dynamic model

SPWLA ABU DHABI CHAPTER TOPICAL CONFERENCE, December 13 and 14, 2021, Reservoir Fluid Surveillance, Today and Beyond

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Overview

- Reservoir characterization/monitoring
 - Fractures
 - Fluids
 - Lithology
- Phases of work
 - 1. Feasibility study + noise test
 - 2. Proof-of-Concept (Data acquisition,

Processing/Interpretation & Integration)

- 3. Case histories (if 1 & 2 are positive)
- Instrumentation KFUPM
- Examples, applicability, efficiency
- Conclusions



Special Event: Hydrocarbon Exploration, June 28-29, 2022, Indonesia



Panagopoulos et al., 2021

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Phases of work (1)



When the second of the second

During the EOR (WAG (Water Alternating Gas) (HC gas) or CO_2) \rightarrow to **improve the flood mobility** \rightarrow to **squeeze more oil** out of the reservoir (>recovery factor).

A <u>monitoring scheme</u> starts \rightarrow field characterization (reservoir properties) \rightarrow accurate fluid mapping (dynamic, \approx 100 m/year)

Before time-lapse monitoring (flooding), a **baseline is required** (the initial model).

DETECT/MONITOR FLUIDS



lapse

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(Seferou et al., 2011)

Phases of work (3)



(Kirkou et al., 2022)

SurHorBor, fallSaturated: BMS Error = 0.0214825

SurflorBork: RMS Error = 0.0547587



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b

Figure 4.12: a) Time lapse ratio No T1/T0; b) Time lapse ratio No T3/T0; c) Time lapse ratio No T8/T0; d) Time lapse ratio No T16/T0.

SurHorFor IniBaturated: RMS Error = 0.0214825

SurHocBorLic BMS Error = 0.4336258

Phases of work (4)



Any project is divided into 3 phases,

Phase 1: 3D Feasibility

- a. <u>Tasks:</u> 3D modeling based on prior info (geology, logs, reservoir simulator, etc.)
- b. <u>Deliverables:</u> 3D Feasibility (timelapse), On-site noise test, Proof-ofconcept pilot plan/survey design
- c. <u>Milestones</u>: Measurable variation of signal above the noise level
- d. <u>Break Point:</u> **Target response** (reservoir parameters' variation) cannot be extracted from noise test.

C and D are link Phase 1 and 2

Phase 1: 3D EM Feasibility workflow for reservoir monitoring



Phases of work (5)

Phase 2:

Proof-of-concept - Can we see reservoir parameter variations?

- a. <u>Tasks:</u>
 - i. Test measurement during a single injection phase (baseline, post-injection), EM-continuous, Gravity - 2 surveys)
- b. <u>Deliverables:</u> Survey data, data processing, time-lapse analysis
- c. <u>Milestones</u>: We can see the reservoir's parameters variation in the individual datasets.
- d. <u>Break Point:</u> There is limited variation of the geophysical responses with petrophysical variations
- e. <u>Decision Point</u>: If results are positive, decide on field pilot within this project or a separate one .



Phase 2: Proof-of-concept DRAFT workflow



Reservoir monitoring: Problem to implementation workflow



Phases of work (6)

<u>Phase</u> **3**: Field pilot study (if Phases 1 and 2 are positive)

Instrumentation (1)

KFUPM CSEM system

A multi-function transmitter is ruggedized, portable, compact yet providing reliable maximum output power of **150 KVA** + **5 sets of sensors** (wireless). In additional to <u>Time domain</u>, it can do <u>Frequency domain</u> and <u>Time Frequency EM (TFEM)</u>

CSAMT, MT, TDEM, Long Offset TEM-LOTEM, IP



Instrumentation & optimum configuration (2)



Instrumentation, remote reference & capabilities (3)

Apparent resistivity (ohm-m)

Phase (degree)





MT QA via Cloud: Quality Assurance RR (1400 miles) & 3D model







FIELDWORK – Dec. 28th – Jan. 2nd



10



Processing – 1D – Near Field



Processing – 1D – Far Field (ST7, 20 km from source)



FLOOD monitoring – EOR @ ARAMCO test field







Steam-flooding makes local changes in resistivity that are large enough to be easily detected.

E-field transients as a function of time. The different in measured signal is in millivolts and easily detectable.



cre ei

Ghawar model building: North-south cross-section









After Colombo et al., 2010

Example Phase 1 output after 3D modeling: Reservoir models, time-lapse resistivity section, surface & borehole





Four different reservoir states several years apart. They indicated that the changes increase with encroaching waterflood.



Receiver above water flood at 2 km depth





Geothermal Exploration in Hungary









After Yu et al., 2010

Geothermal Exploration in Hungary



After Yu et al., 2010



Total success! (4 MW)





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Geothermal Exploration (May 13-22) - FINAL experimental geometry



CPG Geo

Geothermal Exploration (May 13-22)



- Ground truthing of the geological map and tectonic features.
- Record of spectral signatures of different geological units.





Geothermal Exploration (May 13-22)





Use of **aeromagnetic data** (SGS) to estimate the **Curie depth estimations** (the isotherm of 580 °C). This, with the surface temperature as reported from different publications/reports can give me an average estimate of the,

Geothermal Gradient
$$\frac{\partial T}{\partial z} = \frac{T_{Curie} - T_{surface}}{z_b} \left(in \frac{^{\circ}C}{km} \right)$$
 Heat Flow $Hf = k * \frac{\partial T}{\partial z} \left(in \frac{mW}{m^2} \right)$
k=thermal conductivity
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Shallow Geothermal Exploration (June 10-22, 2022)

16 MT stations
6 AMT stations
242 gravity stations
10 water boreholes
1.2 Km seismic
2 GPR profiles

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CONCLUSIONS

- CSEM is well suited for fluid imaging
- Depth 1 to 6 km requires high power Tx (150 KVA)
- O&G, Geothermal: use in exploration & production
- CO2 storage: monitoring & with seismic for seal integrity
 - Combined seismic/EM Same crew = > 50% saving
 - Same instruments record microseismic/EM acquisition
- Interpretation/integration
 - CSEM: 3D anisotropic model available
 - Integrated interpretation
- MUST: Calibrate calibrate calibrate

Future plans:

- Implement more ML/AI
- Acquire denser data: Seismic & EM
- Use EM for monitoring
- Integrate surface with borehole
- Integrate land & marine

